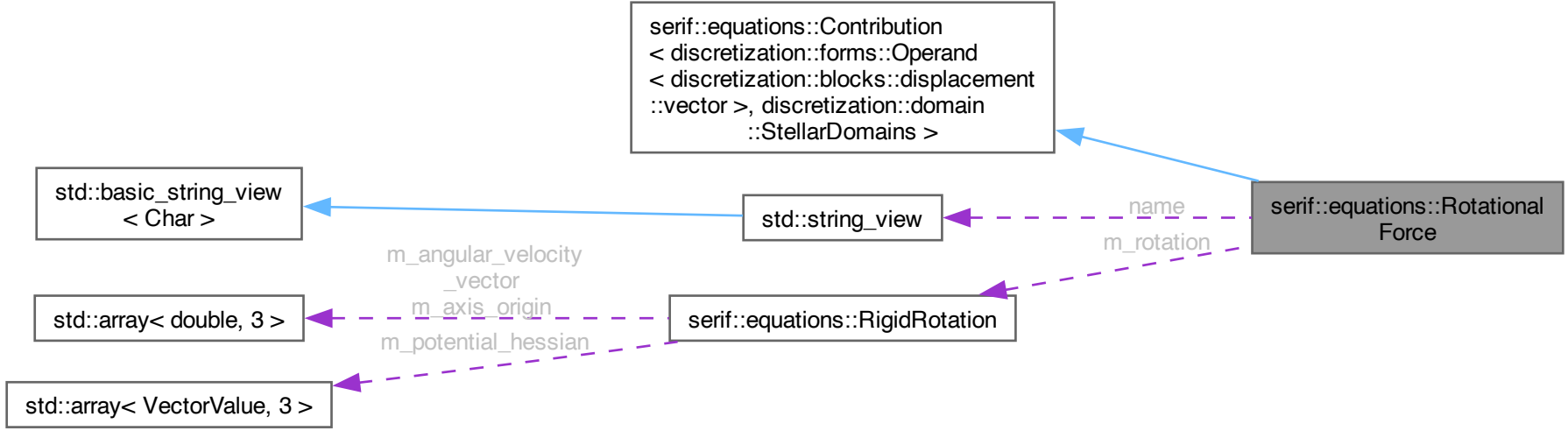

serif::equations::Contribution
< discretization::forms::Operand
< discretization::blocks::displacement
::vector >, discretization::domain
::StellarDomains >
std::basic_string_view
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std::string_view
name
serif::equations::Rotational
Force
m_rotation
m_angular_velocity
_vector
m_axis_origin
std::array< double, 3 >
serif::equations::RigidRotation
m_potential_hessian
std::array< VectorValue, 3 >