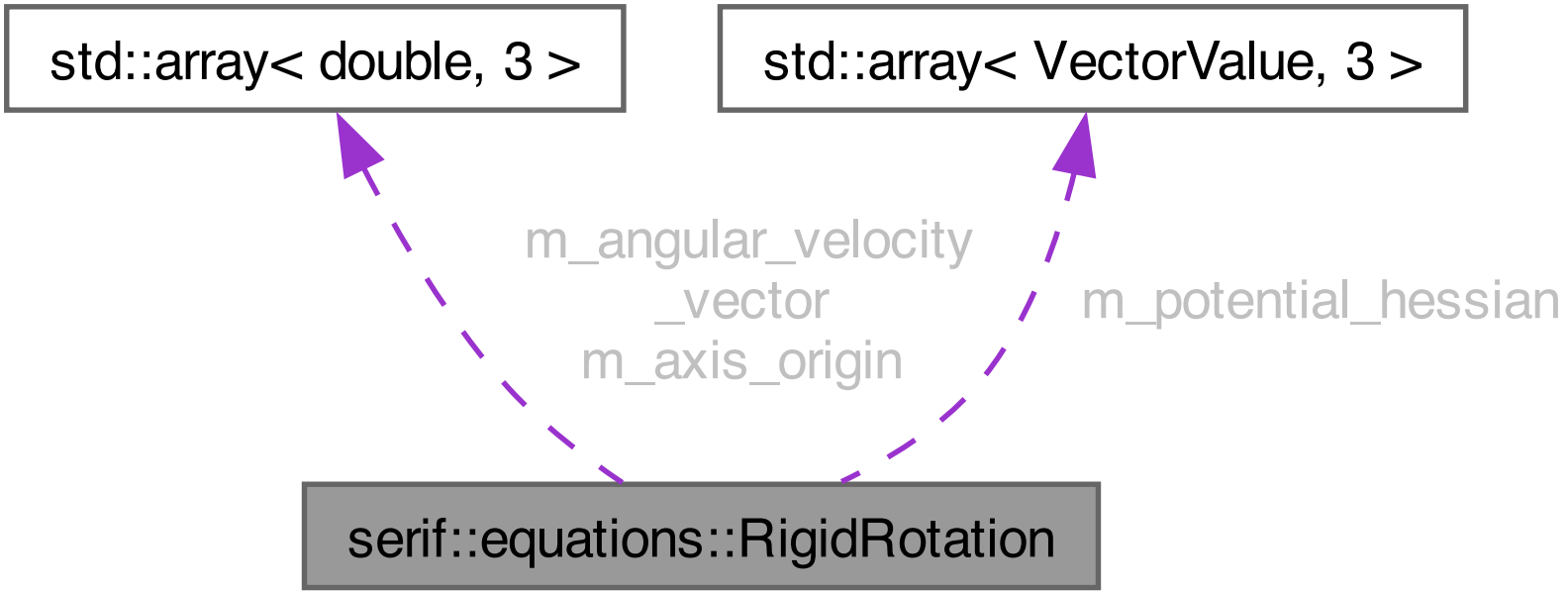

std::array< double, 3 >
std::array< VectorValue, 3 >
m_angular_velocity
_vector
m_axis_origin
m_potential_hessian
serif::equations::RigidRotation