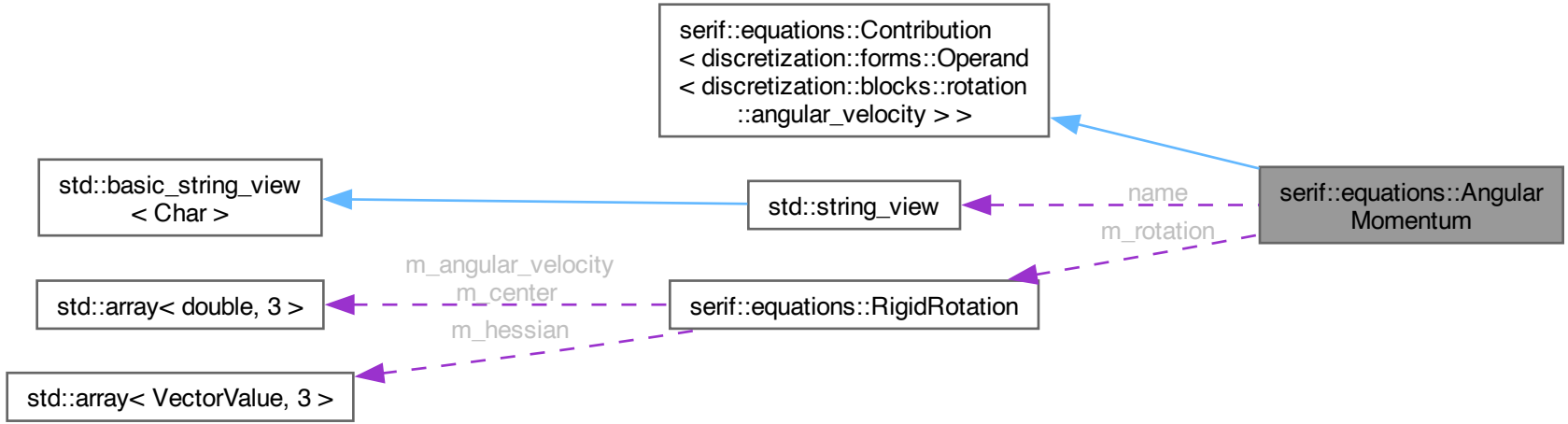

serif::equations::Contribution
< discretization::forms::Operand
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::angular_velocity > >
std::basic_string_view
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name
serif::equations::Angular
Momentum
m_rotation
m_angular_velocity
m_center
std::array< double, 3 >
serif::equations::RigidRotation
m_hessian
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